

Designing Quantum Technology with Optimal Control

Michael Goerz
Army Research Lab

Rigetti Computing Seminar
Berkeley

March 27, 2018

controllable Hamiltonian:

$$\hat{H} = \hat{H}_0 + u_1(t)\hat{H}_1 + u_2(t)\hat{H}_2 + \dots$$

controllable Hamiltonian:

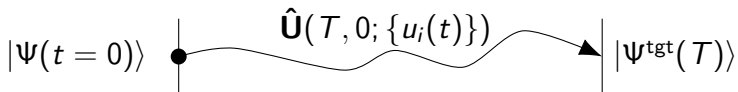
$$\hat{H} = \hat{H}_0 + u_1(t)\hat{H}_1 + u_2(t)\hat{H}_2 + \dots$$

goal: steer quantum system in some desired way

controllable Hamiltonian:

$$\hat{H} = \hat{H}_0 + u_1(t)\hat{H}_1 + u_2(t)\hat{H}_2 + \dots$$

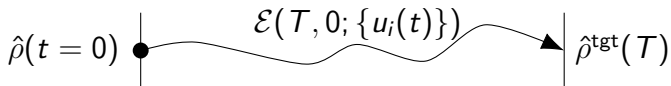
goal: steer quantum system in some desired way



controllable Hamiltonian:

$$\hat{H} = \hat{H}_0 + u_1(t)\hat{H}_1 + u_2(t)\hat{H}_2 + \dots$$

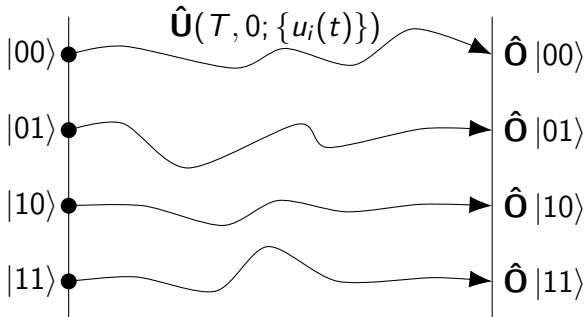
goal: steer quantum system in some desired way



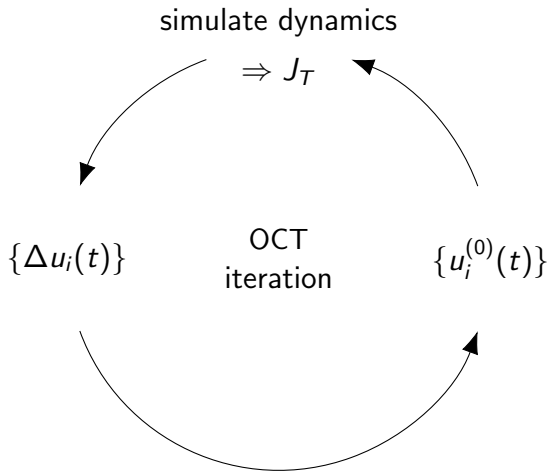
controllable Hamiltonian:

$$\hat{H} = \hat{H}_0 + u_1(t)\hat{H}_1 + u_2(t)\hat{H}_2 + \dots$$

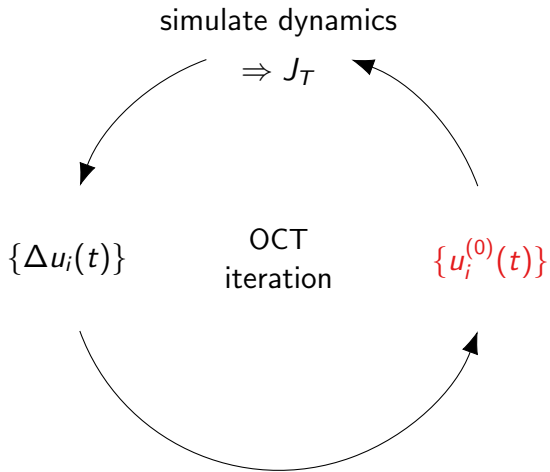
goal: steer quantum system in some desired way



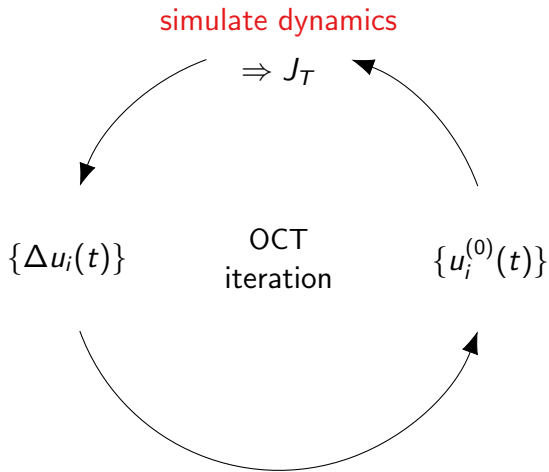
numerical optimal control: iterative improvement



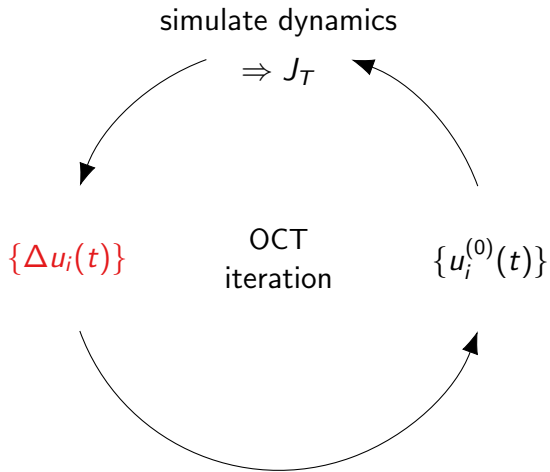
numerical optimal control: iterative improvement



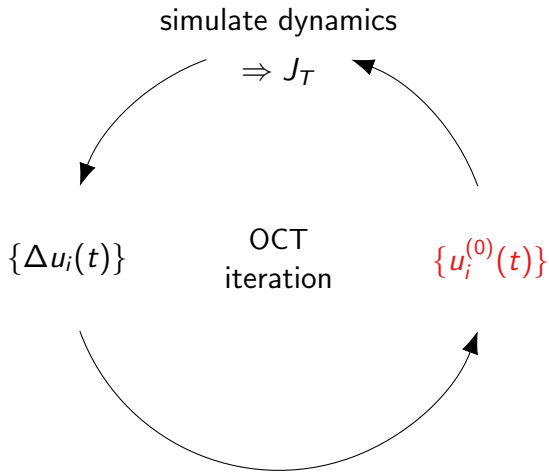
numerical optimal control: iterative improvement



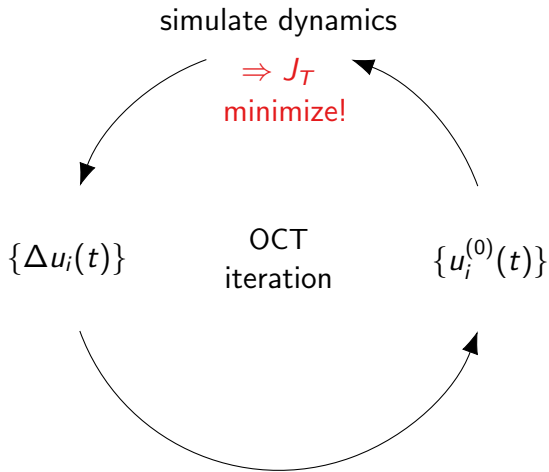
numerical optimal control: iterative improvement



numerical optimal control: iterative improvement



numerical optimal control: iterative improvement



Hamiltonian design

Hamiltonian design

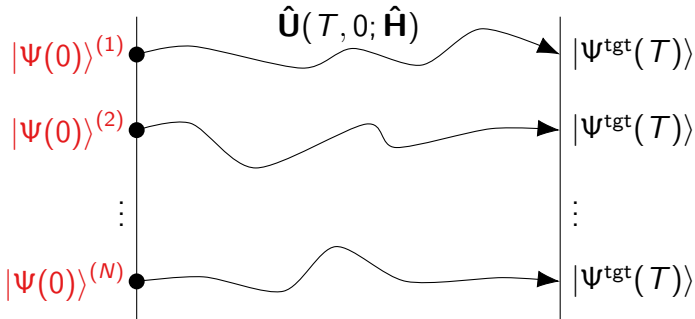
- quantum speed limit

Hamiltonian design

- quantum speed limit
- robustness – experimental noise

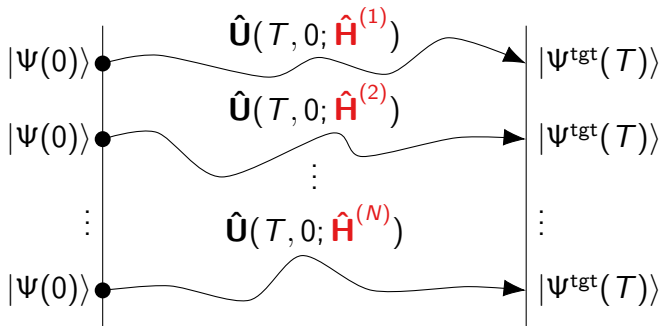
Hamiltonian design

- quantum speed limit
- robustness – experimental noise



Hamiltonian design

- quantum speed limit
- robustness – experimental noise



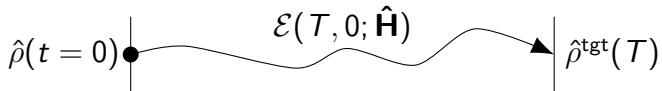
\Rightarrow Goerz et al. Phys. Rev. A 90, 032329 (2014)

Hamiltonian design

- quantum speed limit
- robustness – experimental noise
- robustness – quantum noise

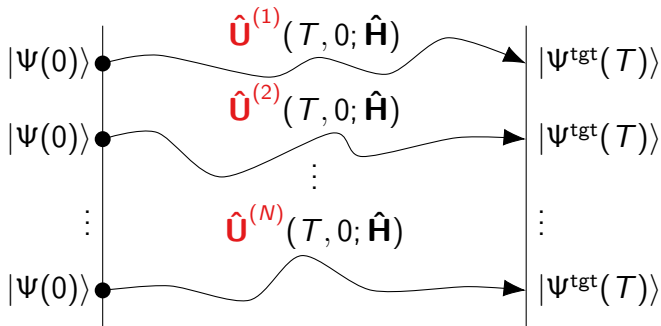
Hamiltonian design

- quantum speed limit
- robustness – experimental noise
- robustness – quantum noise



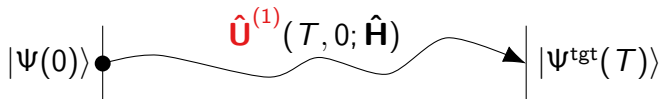
Hamiltonian design

- quantum speed limit
- robustness – experimental noise
- robustness – quantum noise



Hamiltonian design

- quantum speed limit
- robustness – experimental noise
- robustness – quantum noise



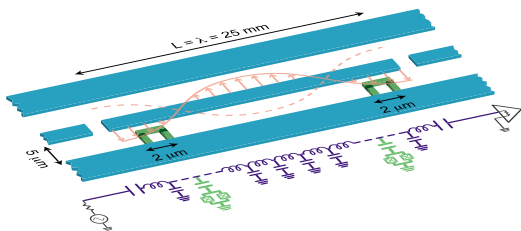
single trajectory can be enough!

\Rightarrow Goerz, Jacobs. arXiv:1801.04382

Charting the circuit QED design landscape using optimal control theory

Goerz et al. npj Quantum Information 3, 37 (2017)

two transmons with shared transmission line bus:

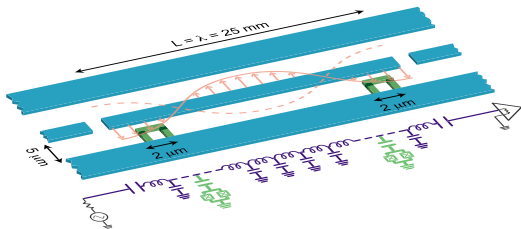


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{\mathbf{a}}^\dagger \hat{\mathbf{a}} + \omega_1 \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 + \omega_2 \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 + \frac{\alpha_1}{2} \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 \hat{\mathbf{b}}_1 + \frac{\alpha_2}{2} \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 \hat{\mathbf{b}}_2$$

$$+ g_1 (\hat{\mathbf{b}}_1^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_1 \hat{\mathbf{a}}^\dagger) + g_2 (\hat{\mathbf{b}}_2^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_2 \hat{\mathbf{a}}^\dagger) + u^*(t) \hat{\mathbf{a}} + u(t) \hat{\mathbf{a}}^\dagger$$

two transmons with shared transmission line bus:

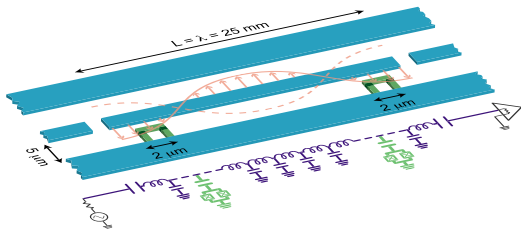


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

two transmons with shared transmission line bus:

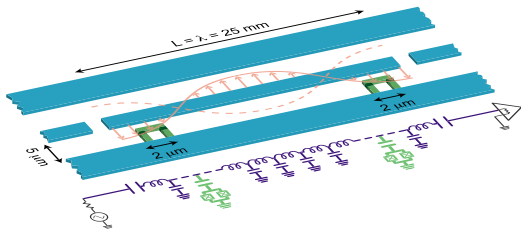


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

two transmons with shared transmission line bus:

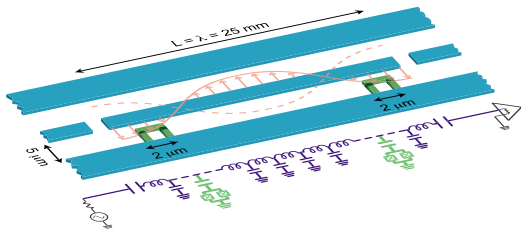


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

two transmons with shared transmission line bus:

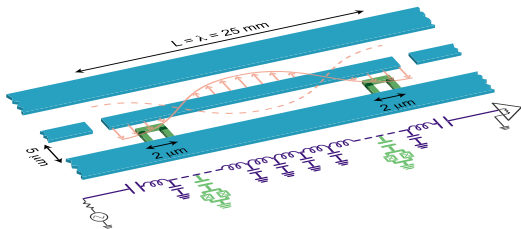


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{\mathbf{a}}^\dagger \hat{\mathbf{a}} + \omega_1 \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 + \omega_2 \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 + \frac{\alpha_1}{2} \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 \hat{\mathbf{b}}_1 + \frac{\alpha_2}{2} \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 \hat{\mathbf{b}}_2$$

$$+ g_1 (\hat{\mathbf{b}}_1^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_1 \hat{\mathbf{a}}^\dagger) + g_2 (\hat{\mathbf{b}}_2^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_2 \hat{\mathbf{a}}^\dagger) + u^*(t) \hat{\mathbf{a}} + u(t) \hat{\mathbf{a}}^\dagger$$

two transmons with shared transmission line bus:

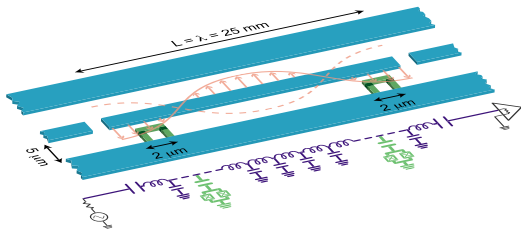


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

two transmons with shared transmission line bus:

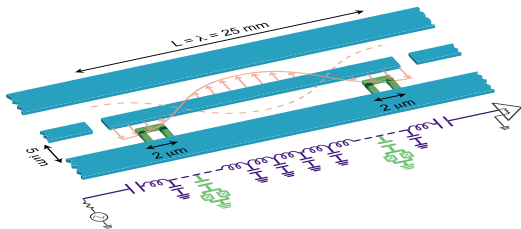


Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

two transmons with shared transmission line bus:



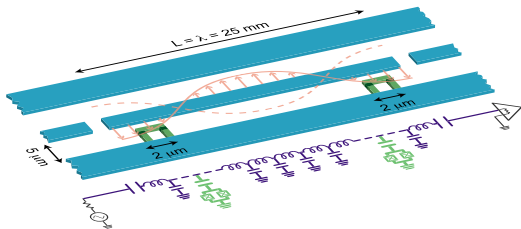
Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{\mathbf{a}}^\dagger \hat{\mathbf{a}} + \omega_1 \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 + \omega_2 \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 + \frac{\alpha_1}{2} \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 \hat{\mathbf{b}}_1 + \frac{\alpha_2}{2} \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 \hat{\mathbf{b}}_2$$

$$+ g_1 (\hat{\mathbf{b}}_1^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_1 \hat{\mathbf{a}}^\dagger) + g_2 (\hat{\mathbf{b}}_2^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_2 \hat{\mathbf{a}}^\dagger) + u^*(t) \hat{\mathbf{a}} + u(t) \hat{\mathbf{a}}^\dagger$$

What are the best parameters for a quantum computer?

two transmons with shared transmission line bus:



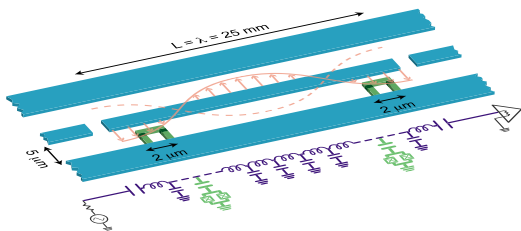
Blais et al. PRA 75, 032329 (2007)

$$\hat{H} = \omega_c \hat{\mathbf{a}}^\dagger \hat{\mathbf{a}} + \omega_1 \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 + \omega_2 \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 + \frac{\alpha_1}{2} \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1^\dagger \hat{\mathbf{b}}_1 \hat{\mathbf{b}}_1 + \frac{\alpha_2}{2} \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2^\dagger \hat{\mathbf{b}}_2 \hat{\mathbf{b}}_2$$

$$+ g_1 (\hat{\mathbf{b}}_1^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_1 \hat{\mathbf{a}}^\dagger) + g_2 (\hat{\mathbf{b}}_2^\dagger \hat{\mathbf{a}} + \hat{\mathbf{b}}_2 \hat{\mathbf{a}}^\dagger) + u^*(t) \hat{\mathbf{a}} + u(t) \hat{\mathbf{a}}^\dagger$$

parameter landscape: $\Delta_c/g,$ Δ_2/α

two transmons with shared transmission line bus:



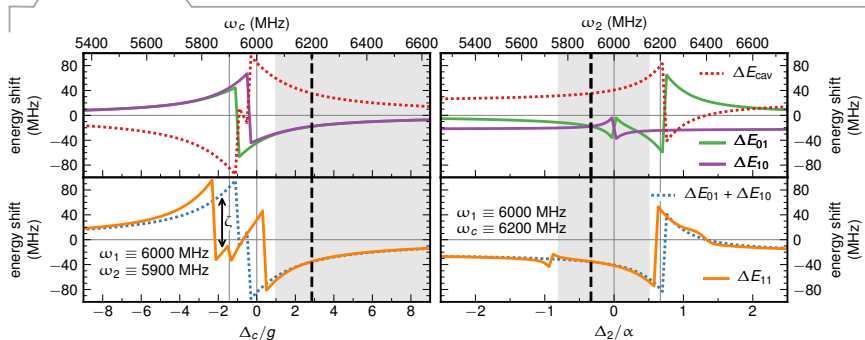
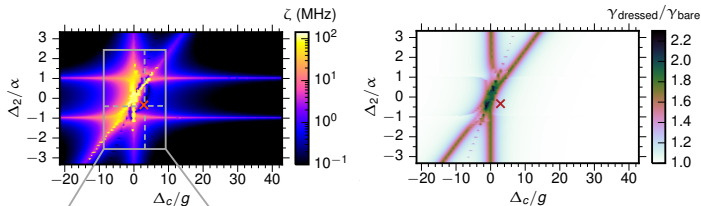
Blais et al. PRA 75, 032329 (2007)

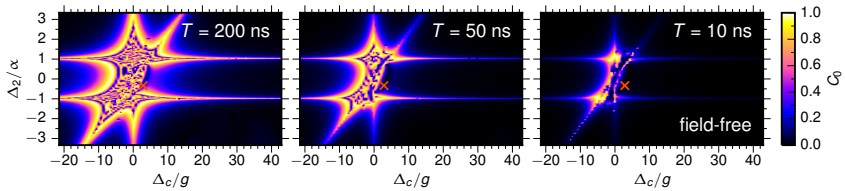
$$\hat{H} = \omega_c \hat{a}^\dagger \hat{a} + \omega_1 \hat{b}_1^\dagger \hat{b}_1 + \omega_2 \hat{b}_2^\dagger \hat{b}_2 + \frac{\alpha_1}{2} \hat{b}_1^\dagger \hat{b}_1^\dagger \hat{b}_1 \hat{b}_1 + \frac{\alpha_2}{2} \hat{b}_2^\dagger \hat{b}_2^\dagger \hat{b}_2 \hat{b}_2$$

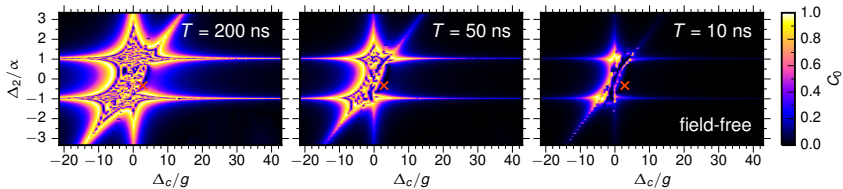
$$+ g_1 (\hat{b}_1^\dagger \hat{a} + \hat{b}_1 \hat{a}^\dagger) + g_2 (\hat{b}_2^\dagger \hat{a} + \hat{b}_2 \hat{a}^\dagger) + u^*(t) \hat{a} + u(t) \hat{a}^\dagger$$

Logical basis: eigenstates of \hat{H} (“dressed states”)

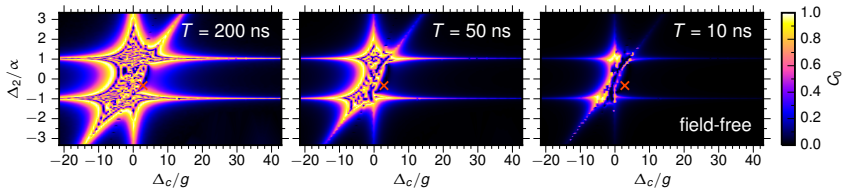
properties for field-free Hamiltonian:



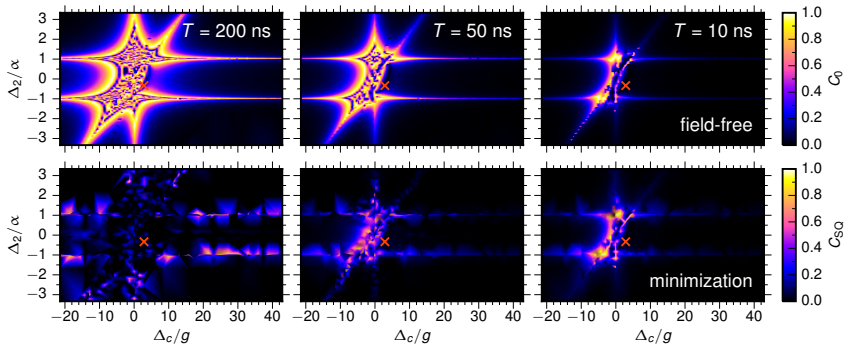


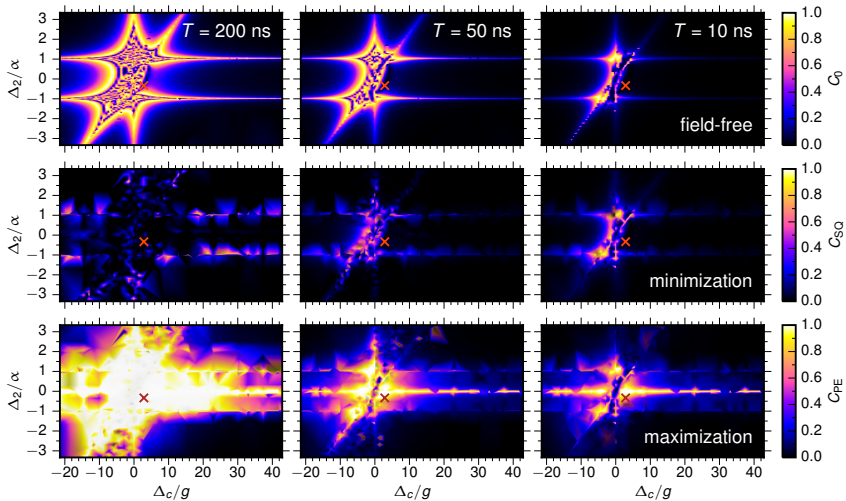


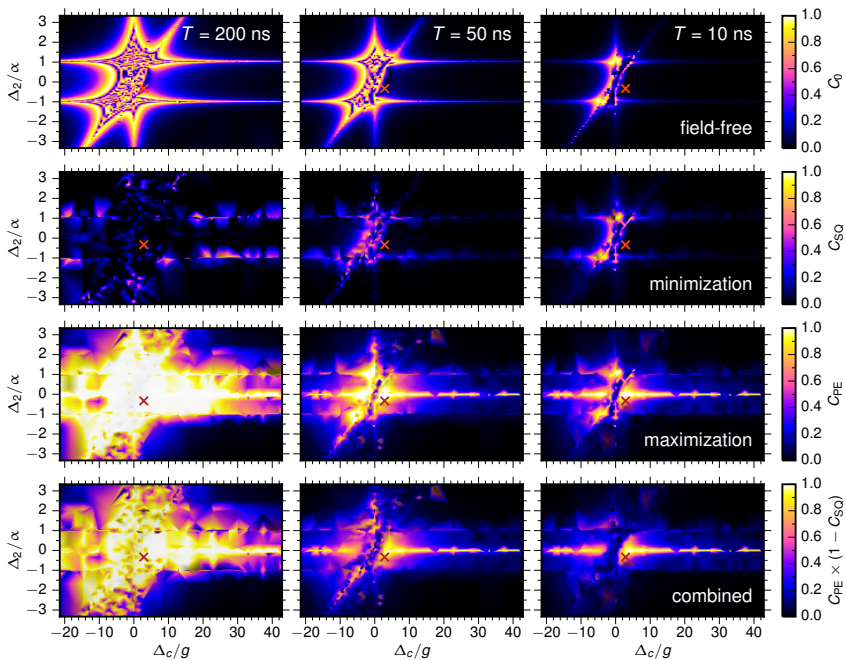
universal quantum computing:
 perfect entangler *and* local gates

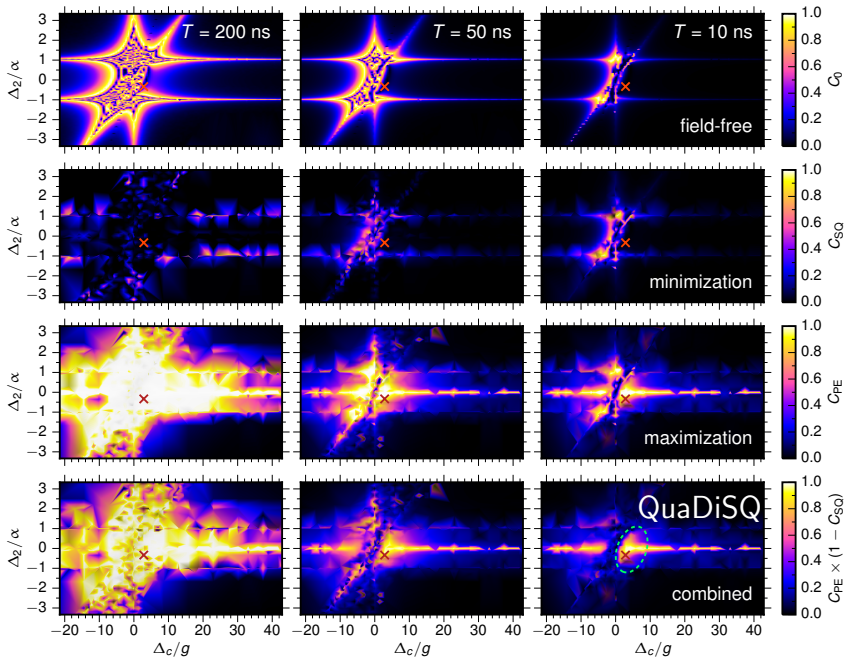


optimize for maximum / minimum entanglement







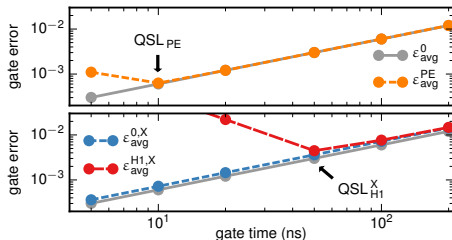


optimize for *specific* set of universal gates:

- Hadamard, Phase single qubit
- BGATE entangler

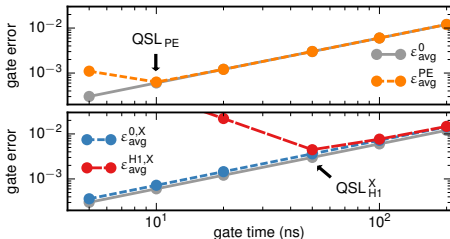
optimize for *specific* set of universal gates:

- Hadamard, Phase single qubit
- BGATE entangler



optimize for *specific* set of universal gates:

- Hadamard, Phase single qubit
- BGATE entangler



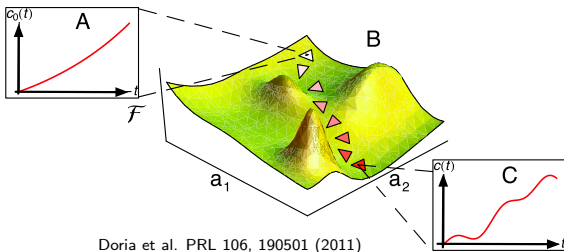
minimum gate duration: 50 ns

gate errors:

- 10^{-4} without dissipation
- 10^{-3} with dissipation

optimal control methods

gradient-free optimization



e.g. Nelder-Mead (simplex), genetic algorithms...

gradient-ascent pulse engineering

$$J_T = 1 - \langle\langle \hat{\rho}(0) | \mathcal{E}_1^\dagger \dots \mathcal{E}_j^\dagger \dots \mathcal{E}_N^\dagger | \hat{\mathbf{P}}_{\text{tgt}} \rangle\rangle$$

with $\mathcal{E}_j \equiv \mathcal{E}(t_j, t_{j-1}; u_{ij})$ and $u_{ij} \equiv u_i([t_{j-1}, t_j])$

gradient-ascent pulse engineering

$$J_T = 1 - \langle\langle \hat{\rho}(0) | \mathcal{E}_1^\dagger \dots \mathcal{E}_j^\dagger \dots \mathcal{E}_N^\dagger | \hat{\mathbf{P}}_{\text{tgt}} \rangle\rangle$$

with $\mathcal{E}_j \equiv \mathcal{E}(t_j, t_{j-1}; u_{ij})$ and $u_{ij} \equiv u_i([t_{j-1}, t_j])$

update
$$\Delta u_{ij} \propto \frac{\partial J_T}{\partial u_{ij}} = - \langle\langle \hat{\mathbf{P}}^{(0)}(t_j) \left| \frac{\partial \mathcal{E}_j}{\partial u_{ij}} \right| \hat{\rho}^{(0)}(t_{j-1}) \rangle\rangle$$

[Khaneja et al. J. Magnet. Res. 172, 296 (2005)]

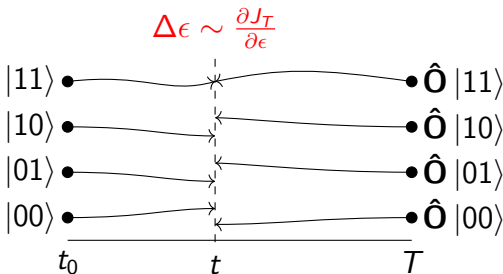
gradient-ascent pulse engineering

$$J_T = 1 - \langle\langle \hat{\rho}(0) | \mathcal{E}_1^\dagger \dots \mathcal{E}_j^\dagger \dots \mathcal{E}_N^\dagger | \hat{\mathbf{P}}_{\text{tgt}} \rangle\rangle$$

with $\mathcal{E}_j \equiv \mathcal{E}(t_j, t_{j-1}; u_{ij})$ and $u_{ij} \equiv u_i([t_{j-1}, t_j])$

update
$$\Delta u_{ij} \propto \frac{\partial J_T}{\partial u_{ij}} = - \langle\langle \hat{\mathbf{P}}^{(0)}(t_j) \left| \frac{\partial \mathcal{E}_j}{\partial u_{ij}} \right| \hat{\rho}^{(0)}(t_{j-1}) \rangle\rangle$$

[Khaneja et al. J. Magnet. Res. 172, 296 (2005)]



Krotov's method

auxiliary functional

$$J = J_T + \sum_i \frac{\lambda_i}{S_i(t)} \int_0^T \overbrace{|u_i^{(1)}(t) - u_i^{(0)}(t)|^2}^{|\Delta u_i(t)|^2} dt$$

u_i^{ref}

different functional in every iteration!

Krotov's method

auxiliary functional

$$J = J_T + \sum_i \frac{\lambda_i}{S_i(t)} \int_0^T \overbrace{|u_i^{(1)}(t) - \underbrace{u_i^{(0)}(t)}_{u_i^{\text{ref}}}|^2}_{|\Delta u_i(t)|^2} dt$$

different functional in every iteration!

update
$$\Delta u_i(t) = \frac{S_i(t)}{\lambda_i} \Im \left\langle \left\langle \hat{\Xi}^{(0)}(t) \left| \frac{\partial \mathcal{L}}{\partial u_i(t)} \right| \hat{\rho}^{(1)}(t) \right\rangle \right\rangle$$

boundary condition
$$\hat{\Xi}^{(0)}(T) = \frac{J_T}{\langle \rho \rangle} = \hat{\mathbf{P}}_{\text{tgt}}$$

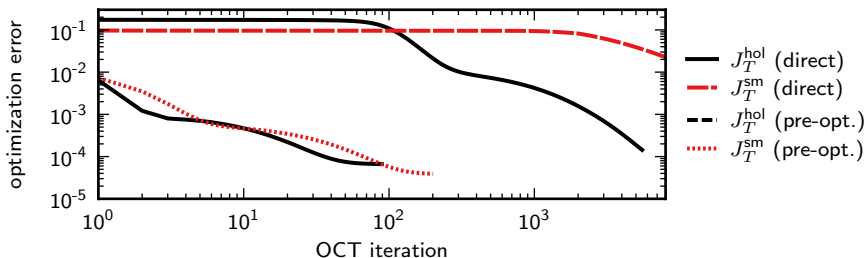
[Reich et al. J. Chem. Phys. 136, 104103 (2012)]

“hybrid” (multi-stage) methods

- 1 Start with analytical formula, optimize free parameter with **simplex**
- 2 Use simplex-optimized control as starting point for **gradient-based** method

“hybrid” (multi-stage) methods

- 1 Start with analytical formula, optimize free parameter with **simplex**
- 2 Use simplex-optimized control as starting point for **gradient-based** method

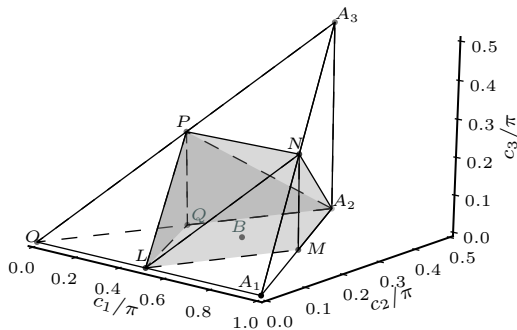


⇒ Goerz et al. EPJ Quantum Tech. 2, 21 (2015)

advanced functionals

optimizing for entanglement

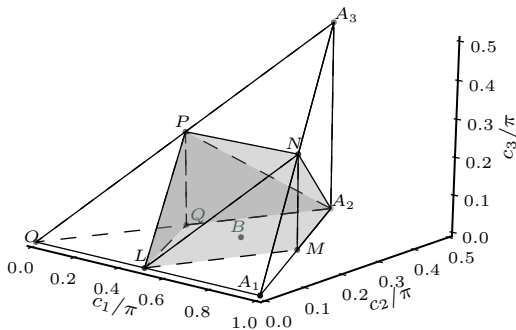
optimizing for entanglement



Cartan decomposition:

$$\hat{U} = \hat{\mathbf{k}}_1 \exp \left[\frac{i}{2} (c_1 \hat{\sigma}_x \hat{\sigma}_x + c_2 \hat{\sigma}_y \hat{\sigma}_y + c_3 \hat{\sigma}_z \hat{\sigma}_z) \right] \hat{\mathbf{k}}_2$$

optimizing for entanglement



Cartan decomposition:

$$\hat{U} = \hat{\mathbf{k}}_1 \exp \left[\frac{i}{2} (c_1 \hat{\sigma}_x \hat{\sigma}_x + c_2 \hat{\sigma}_y \hat{\sigma}_y + c_3 \hat{\sigma}_z \hat{\sigma}_z) \right] \hat{\mathbf{k}}_2$$

\Rightarrow application: Goerz et al. Phys. Rev. A 91, 062307 (2015)

quantum gates in open quantum systems

Hilbert space

$$J_T = 1 - \frac{1}{16} \left| \sum_{i=1}^4 \langle i | \hat{\mathbf{O}}^\dagger \hat{\mathbf{U}} | i \rangle \right|^2 ; \quad |i\rangle \in \{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$$

quantum gates in open quantum systems

Hilbert space

$$J_T = 1 - \frac{1}{16} \left| \sum_{i=1}^4 \langle i | \hat{\mathbf{O}}^\dagger \hat{\mathbf{U}} | i \rangle \right|^2; \quad |i\rangle \in \{|00\rangle, |01\rangle, |10\rangle, |11\rangle\}$$

Liouville space

⇒ Goerz et al. NJP 16, 055012 (2014)

$$J_T = 1 - \sum_{i=1}^3 \frac{w_i}{\text{tr}[\hat{\rho}_i^2]} \Re \{ \text{tr} [\hat{\rho}_i^{\text{tgt}} \hat{\rho}_i(T)] \}$$

$$\hat{\rho}_1 = \frac{1}{20} \begin{pmatrix} 8 & 0 & 0 & 0 \\ 0 & 6 & 0 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}, \quad \hat{\rho}_2 = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}, \quad \hat{\rho}_3 = \frac{1}{4} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

populations

phases

subspace

Summary

Summary

- optimal control as Hamiltonian design tool
 - fast protocols
 - robustness

Summary

- optimal control as Hamiltonian design tool
 - fast protocols
 - robustness
- exploring parameter landscapes: transmon qubits

Summary

- optimal control as Hamiltonian design tool
 - fast protocols
 - robustness
- exploring parameter landscapes: transmon qubits
- algorithms: gradient-free; GRAPE, Krotov

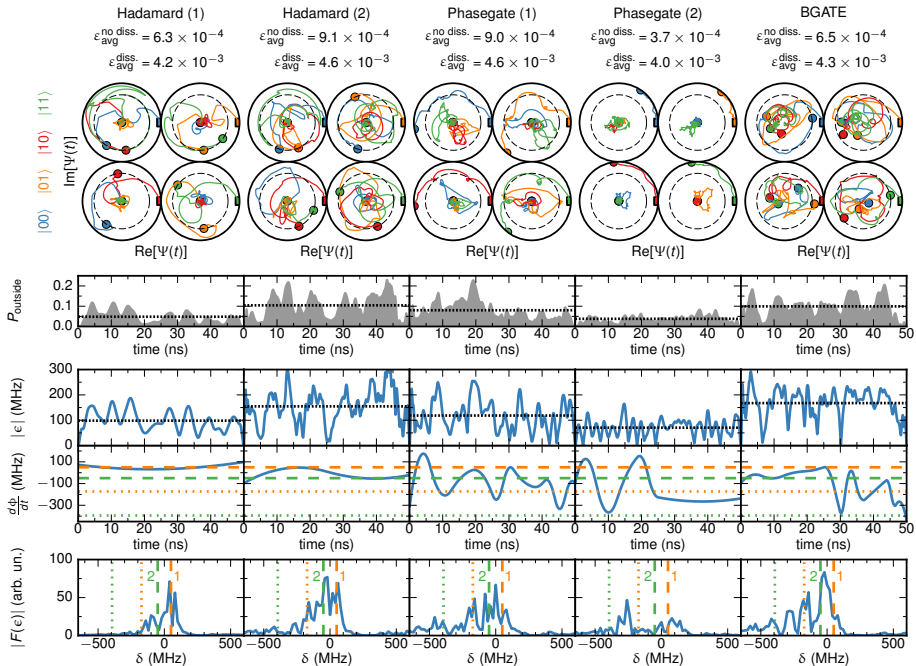
Summary

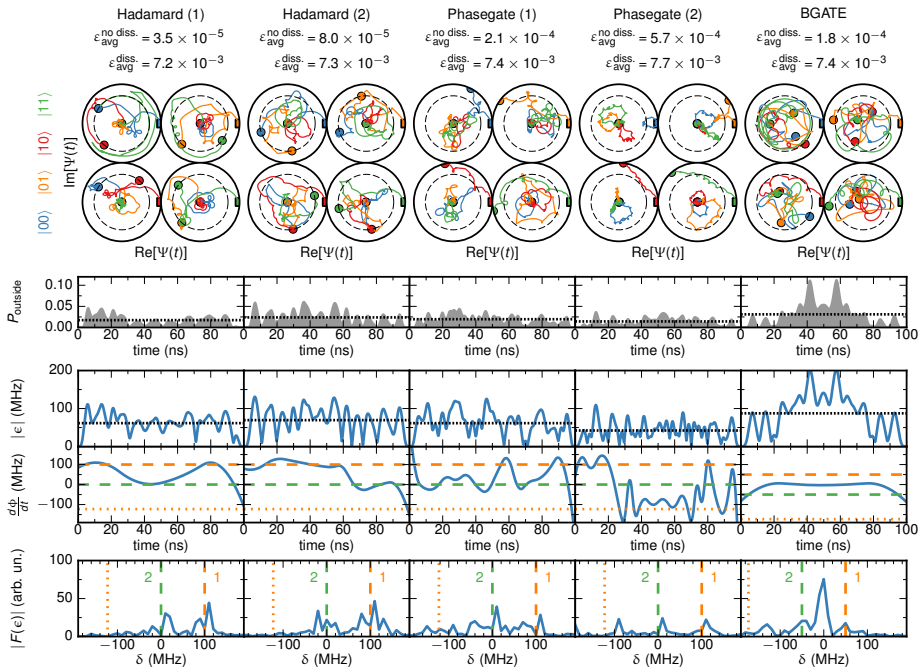
- optimal control as Hamiltonian design tool
 - fast protocols
 - robustness
- exploring parameter landscapes: transmon qubits
- algorithms: gradient-free; GRAPE, Krotov
- advanced functionals: Weyl-chamber, tracking density matrices

Summary

- optimal control as Hamiltonian design tool
 - fast protocols
 - robustness
- exploring parameter landscapes: transmon qubits
- algorithms: gradient-free; GRAPE, Krotov
- advanced functionals: Weyl-chamber, tracking density matrices

Thank You





obtained perfect entanglers in the Weyl chamber:

